



CV

Jørn Lambertsen



Cand. Arch

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Work

- 2016 - Technology Officer - Flow Robotics
- Mechanical Design
 - Prototyping, Research and Development
 - Production, Logistics, Planning
- 2014 - 2016 Research Assistant - IT-University of Copenhagen
- REAL (Robotics, Evolution and Arts Laboratory) Research Group
 - Adaptive Environments Research Group
- 2013 Project: ODICO, Formwork Robotics
- Rhino/Grasshopper/HAL Robot Programming
 - ABB Robotstudio, Robot Control
- 2013 Temp. Teacher - Aarhus School of Architecture
- Rhino/Grasshopper
 - Teaching, Preparation of topology optimization models
- 2011 - 2013 Tutor - Aarhus School of Architecture
- Workshops focusing on 3D-modelling and parametric design

Born: 13 april 1976
Education: Cand. Arch. Arkitektskolen Aarhus

Education

- 2007 - 2013 MA Architecture - Aarhus School of Architecture
10. - Studio Spatial Transformation - Urban Planning
9. Studio Sustainable Transformation - Madrid,
8. - Studio Sustainable Transformation, Aarhus, Hybrid Buildings/Urban Planning
7. - Exchange Student- SUNY at Buffalo, New York - Experimental Buildings,
6. - City and Landscape - Aarhus Harbour - Urban Planning
5. - City and Landscape - Buffalo, NY - Planning and Cityscapes
- 2005 - 2007 Højere Forberedelseseksamen - at VUC Aarhus
- 2003 - 2004 Sønderjyllands Kunstscole - Art School - 2nd Year
- 2002 - 2003 EUC SYD - Tailor, Milinery
- 1996 - 1998 Fri Ungdomsuddannelse
- Sønderjyllands Kunstscole (Art School)
 - Højskolen Strand, Sønderborg
 - EUC SYD Chermics

Short Bio

With a circuitous route to my current work I've been pursuing an artistic career in my youth, with a multitude of odd jobs and experiences to support this, I later delved into architecture and urban planning where I laid the groundwork for working in robotics