



Design & Development

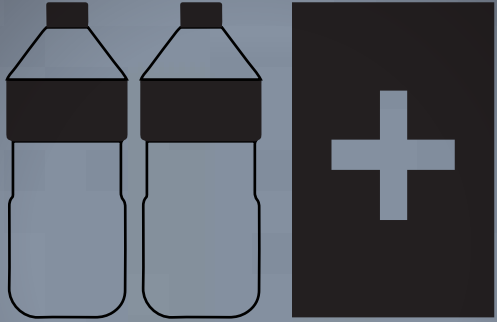


UNLOADED

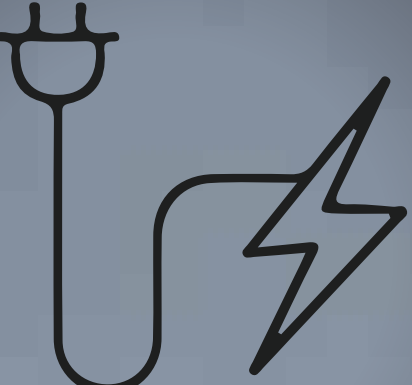
3.7 KG



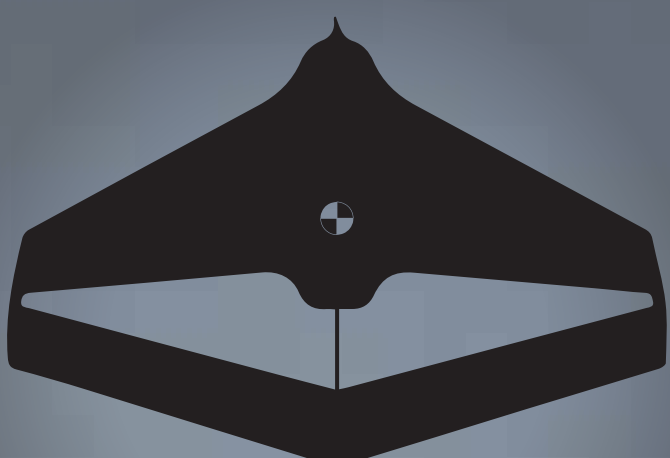
11.5m/s



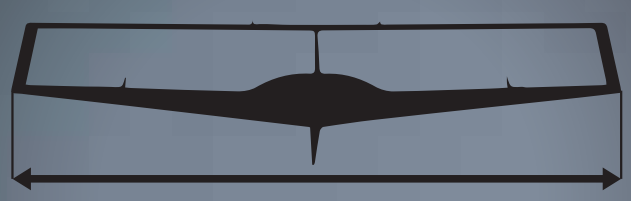
1.6kg



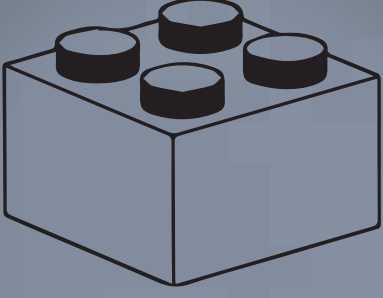
$\epsilon=1.3^*$




INERENTEBLY STABLE



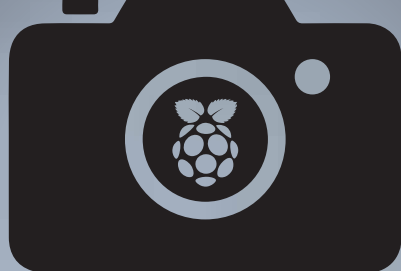
1.5m




Modular design



Pixhawk



Raspberry PI



CATAPULT LAUNCH

*Added efficiency up to 30% compared with same sized wing

①

The team was started by students of the University of Southern Denmark with one goal:

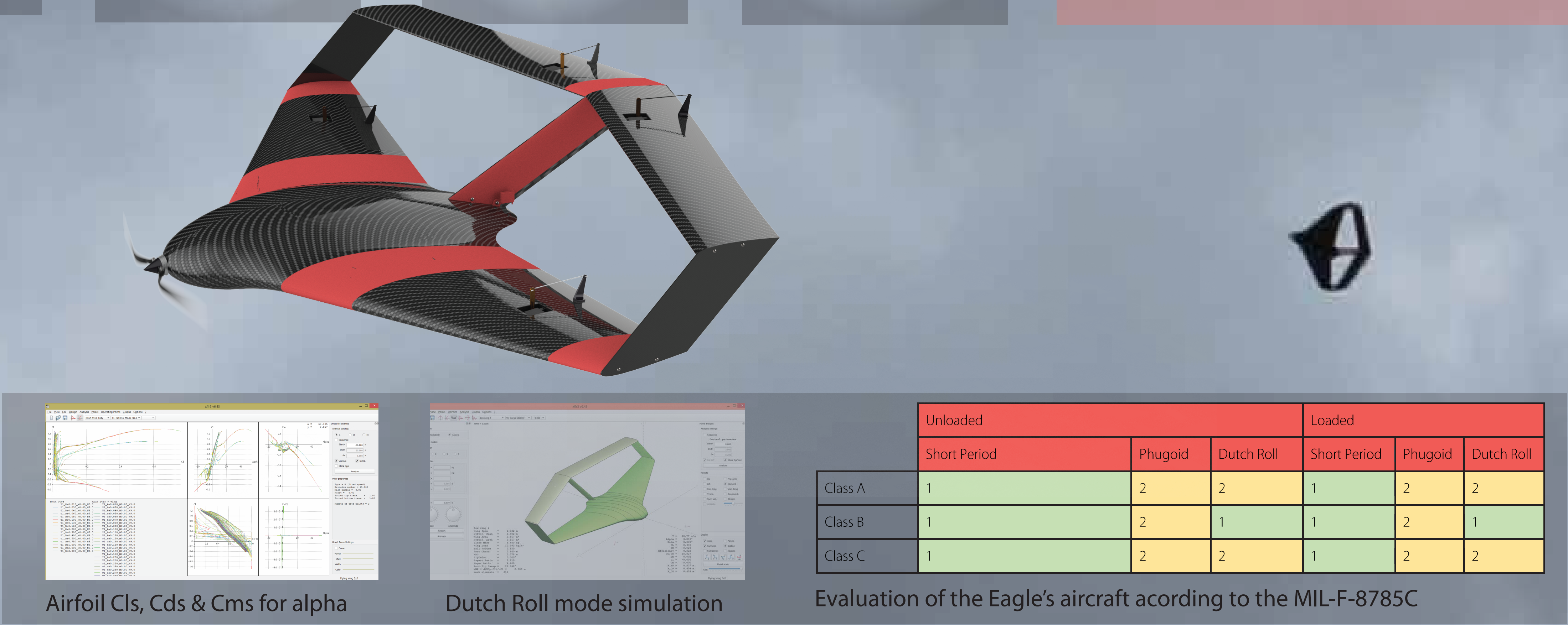
Develop an efficient, modularized and sustainable drone for humanitarian purposes.

With no previous experience in aircraft design or manufacturing, the team embarked on a journey of studying, learning by doing, and the commitment to participate in the IMECHE UAS Challenge.

②

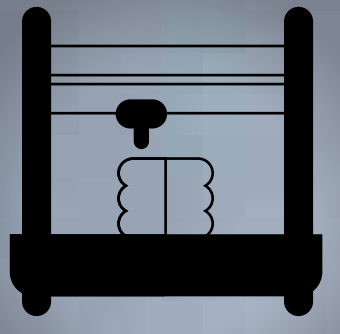
With the constraints defined above, the development process started.

Airfoils were selected to maximize the efficiency for the desired cruising flight conditions. Through an iterative process in XLF5 and in the parametric model of the aircraft, a good flight behaviour was achieved.




Manufacturing & Testing

1st prototype

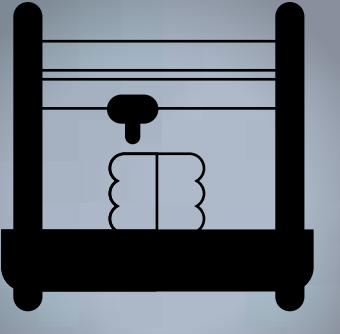


3D PRINTING

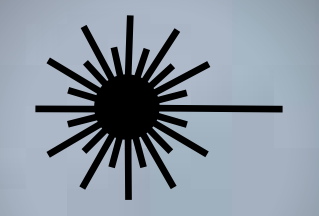


WIND TUNNEL


1st functional prototype



3D PRINTING




LASER CUTTING




HAND LAY-UP


Final product



CNC MILLING



VACCU MOLDING



FOAM CASTING

Problem solving through prototyping:

With the elevated center of gravity due to the box wing configuration and due to the difficulties of acomodating a raised motor, the thrust angle had to be pointed downwards. This problem was found during testing, upon notice of a pitching up tendency of the aircraft while throttling up.

Catapult testing:

The catapult lanches the aircraft with an acceleration of 3Gs. 300 Joules of kinetic energy need to be damped by a spring. After testing and mutiple iterations, a trampoline spring was found to be adequate for dampening the launch car.



③

For the initial prototyping phase, low cost was a priority.

As such, the team used existing equipment available at the university and developed the initial prototypes using desktop 3D printers, a low power laser cutter and hand tools.

With a finished 1:1 scale prototype, it was easier to present the idea and test the behaviour of the drone.

A local company offered to manufacture the molds, while access to the university composite lab was provided to the team.

Innovation, Safety & Enviroment

④

Transportation is one of the largest polluters in the world. In the search for a highly efficient solution that would reduce our energy consumption and increase the operating range of our aircraft, we found a long forgotten idea - the Prandtl plane. This box wing configuration minimizes air drag and, as a result, reaches a theoricall efficiency 30% higher than a conventional design.

⑤

The simple yet resilient monocoque body reinforced with natural hemp fibers ensures longevity and low maintenance requirements, while its modularity makes it easy to repair or replace only the affected components, which reduces the waste produced by using our solution.

Many of the mechanical and electrical components are standardized and commonly sold around the world, making it even easier to repair the airplane and keep it running.



⑥

A strict safety procedure was developed to prevent injuries while the plane is on the ground.

A designated member of the team dictates when it is safe to approach the plane.

The pilot can terminate the mission if desired via a remote kill switch. The autopile can also terminate the flight if it detects an issue.